
Finite-state Strategies in Delay Games

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Motivation

Two goals:

1. Lift the notion of finite-state strategies to delay games.
2. Present uniform framework for solving delay games (which yields finite-state strategies whenever possible).

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2. Present uniform framework for solving delay games (which yields finite-state strategies whenever possible).

Questions:

- What are delay games?
- Why are finite-state strategies important?
- Why do we need a uniform framework?

Delay Games

In this talk, a game is given by an ω -language $L \subseteq (\Sigma_I \times \Sigma_O)^\omega$.

Example

$$\begin{pmatrix} \alpha(0) \\ \beta(0) \end{pmatrix} \begin{pmatrix} \alpha(1) \\ \beta(1) \end{pmatrix} \cdots \in L, \text{ if } \beta(i) = \alpha(i + 2) \text{ for every } i$$

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I: b a b b a b a ...
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- **Fridman, Löding & Z. ('11)**: Nothing non-trivial is solvable for ω -contextfree delay games, unbounded lookahead necessary.

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All recent (positive) results use variations of the same proof idea.

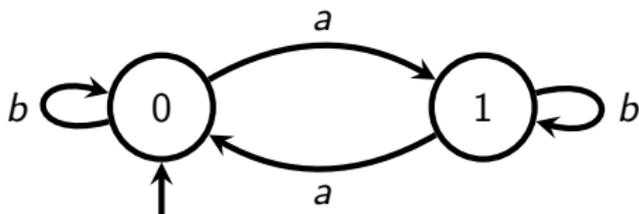
Finite-state Strategies

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- A finite-state strategy is implemented by a finite automaton with output, and therefore finitely represented.

Example



$$w \mapsto |w|_a \bmod 2$$

Why Finite-state Strategies

Finite-state/positional strategies are crucial in many applications of infinite games, e.g.:

- In reactive synthesis, a finite-state winning strategy is a correct-by-construction controller.
- (Modern proofs of) Rabin's theorem rely on positional determinacy of parity games.
- In general, the existence of finite-state strategies enables the application of infinite games.
- Determining the memory requirements is one of the most fundamental tasks for a class of games.

Finite-state Strategies for Delay Games

Disclaimer: We focus here on constant delay!

- A strategy in a delay game is still a map $\sigma: \Sigma_I^* \rightarrow \Sigma_O$.
- So, the classical definition is still applicable.
- By “hardcoding” constant lookahead into the rules of the game, finite-state winning strategies are computable.

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- So, the classical definition is still applicable.
- By “hardcoding” constant lookahead into the rules of the game, finite-state winning strategies are computable.
- However, this notion does not distinguish “past” and “future”.

A (Cautionary) Example

Example

$$L = \left\{ \binom{\alpha}{\alpha} \mid \alpha \in \{0, 1\}^\omega \right\}$$

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I: *a* *a* *b* *a* *a* *b* *b* *b* *a* *a* *a* *a* *b*

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d



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O:	<i>a</i>	<i>a</i>	<i>b</i>	<i>a</i>	<i>a</i>	<i>b</i>	<i>b</i>	<i>b</i>				

A horizontal line with a curly brace underneath spans the last five characters of the top row: *b a a a b*. The letter *d* is positioned above the center of this line.

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$\overbrace{\hspace{4cm}}^d$

- Requires 2^d memory states with constant lookahead d .

Block Games

Distinguishing between past and future: **block games**

- Fix a block length $d > 0$.
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- Player O picks blocks $\bar{b}_i \in \Sigma_O^d$.
- Player O wins, if $(\frac{\bar{a}_0 \bar{a}_1 \bar{a}_2 \dots}{\bar{b}_0 \bar{b}_1 \bar{b}_2 \dots}) \in L$
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- Fix a block length $d > 0$.
- Player I picks blocks $\bar{a}_i \in \Sigma_I^d$.
- Player O picks blocks $\bar{b}_i \in \Sigma_O^d$.
- Player O wins, if $\left(\frac{\bar{a}_0 \bar{a}_1 \bar{a}_2 \dots}{\bar{b}_0 \bar{b}_1 \bar{b}_2 \dots}\right) \in L$
- To account for (constant) lookahead, Player 1 is one move ahead.

Example

$$\left(\begin{array}{c} \alpha(0) \\ \beta(0) \end{array}\right) \left(\begin{array}{c} \alpha(1) \\ \beta(1) \end{array}\right) \dots \in L, \text{ if } \beta(i) = \alpha(i+2) \text{ for every } i$$

I : $b \ a \ b \ a \ b \ a \ b \ b \ a \ b$
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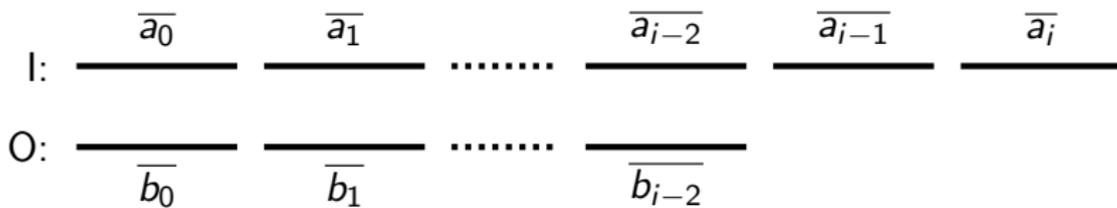
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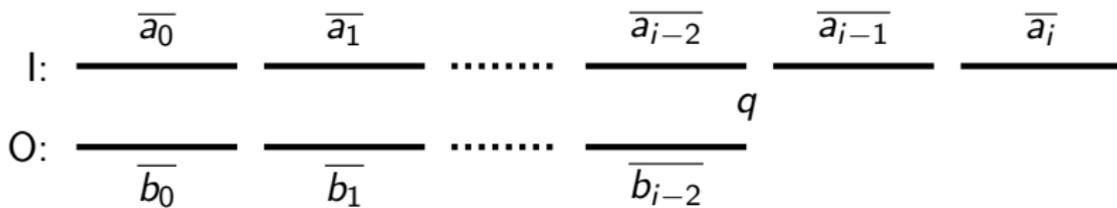
Finite-state Strategies for Block Games

- A finite-state strategy in a block game reads blocks over Σ_I and outputs blocks in Σ_O :



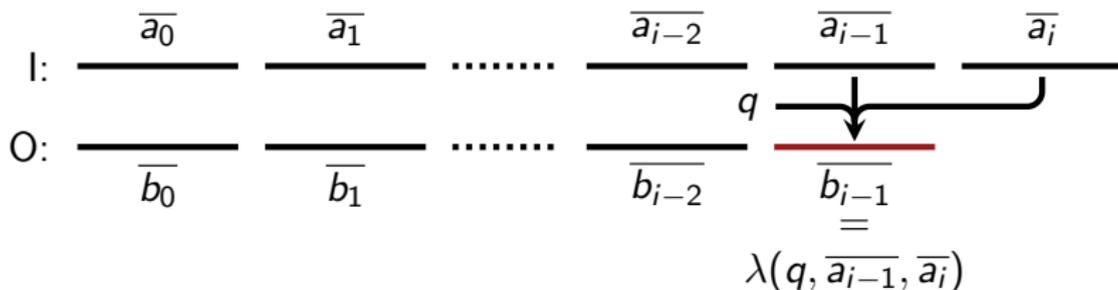
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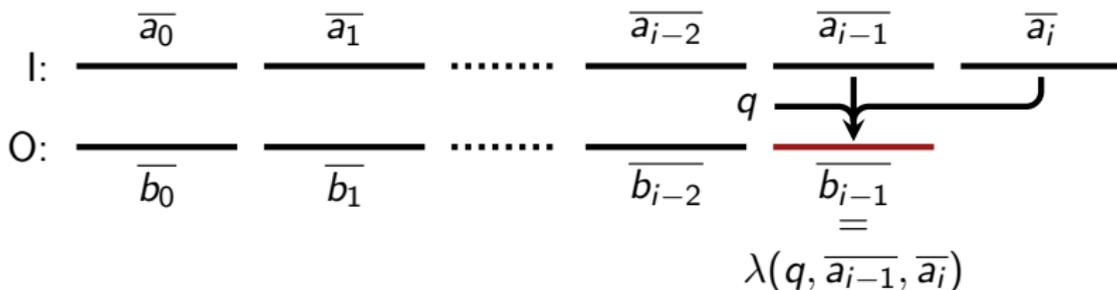
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Note:

- Alphabet now exponential in block length!
- But, we distinguish past and future.
- In particular, state complexity only concerned with past.

Aggregations

- Fix ω -automaton \mathfrak{A} and a finite set M .
- $s: Q^+ \rightarrow M$ is an aggregation for \mathfrak{A} , if for all runs $\rho = \pi_0\pi_1\pi_2 \cdots$ and $\rho' = \pi'_0\pi'_1\pi'_2 \cdots$ with $s(\pi_0)s(\pi_1)s(\pi_2) \cdots = s(\pi'_0)s(\pi'_1)s(\pi'_2) \cdots$: ρ is accepting $\Leftrightarrow \rho'$ is accepting.

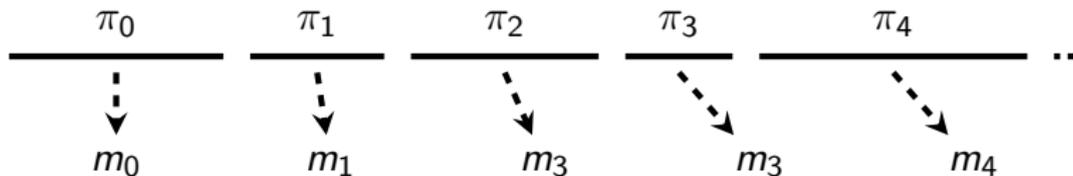
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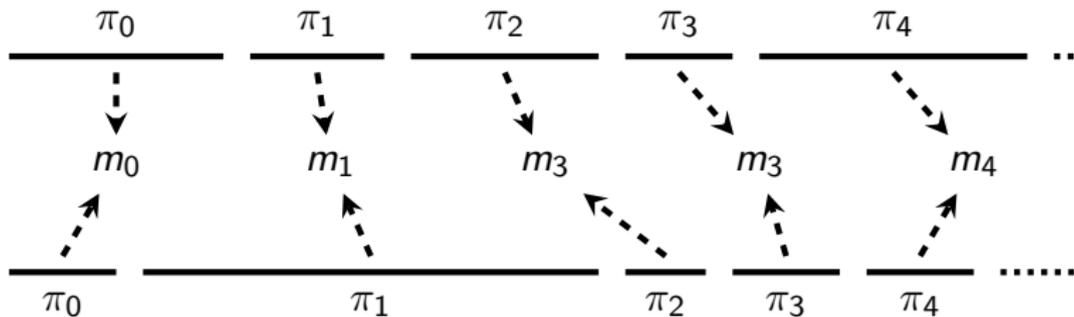
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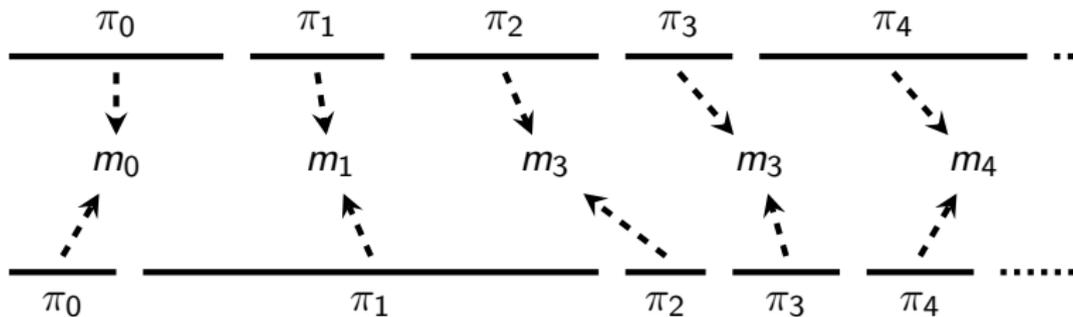
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Example

$q_0 \cdots q_i \mapsto \max_{0 \leq j \leq i} \Omega(q_j)$ is an aggregation for a max-parity automaton with coloring Ω .

Automata Computing Aggregations

Every automaton \mathfrak{M} with input alphabet Q and state set M computes an aggregation $s_{\mathfrak{M}}: Q^+ \rightarrow M$: $s_{\mathfrak{M}}(\pi)$ is the state reached by \mathfrak{M} when processing π .

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Example

$q_0 \cdots q_i \mapsto \max_{0 \leq j \leq i} \Omega(q_j)$ computable by automaton with state set $\Omega(Q)$.

Abstract Block Games

Fix \mathfrak{A} recognizing winning condition $L(\mathfrak{A}) \subseteq (\Sigma_I \times \Sigma_O)^\omega$ and let $s_{\mathfrak{M}}: Q^+ \rightarrow M$ be aggregation for \mathfrak{A} computed by some \mathfrak{M} .

- Define $x \equiv x'$ iff x and x' induce the same behavior in \mathfrak{A} , i.e., the same state changes and the corresponding runs have the same $s_{\mathfrak{M}}$ -value.

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$$\underline{x \in \Sigma_I^*}$$

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$$\frac{x \in \Sigma_I^*}{y \in \Sigma_O^*}$$

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q_0

q_1

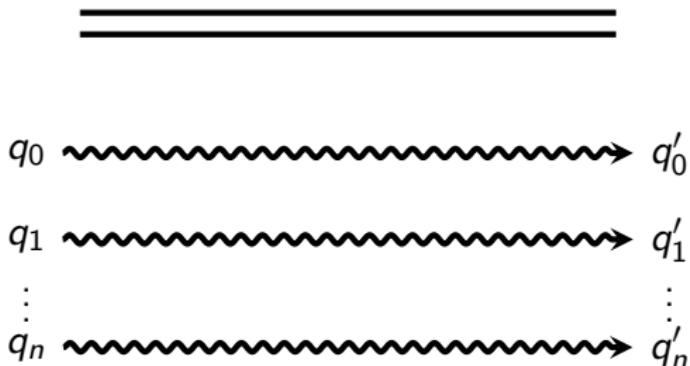
\vdots

q_n

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- \equiv has index at most $2^{|Q|^2|M|}$.

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The abstract block game is played as follows:

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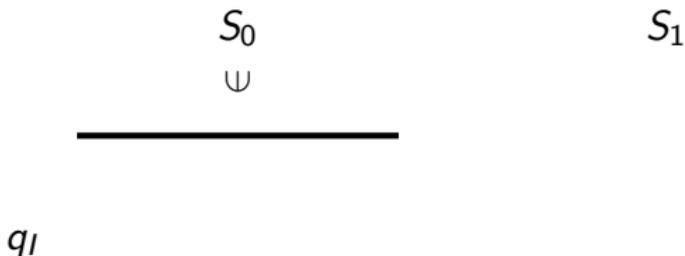
S_1

q_I

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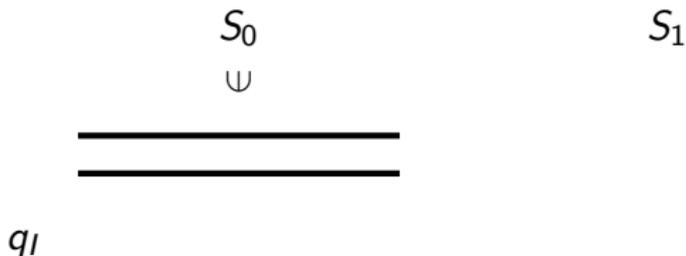
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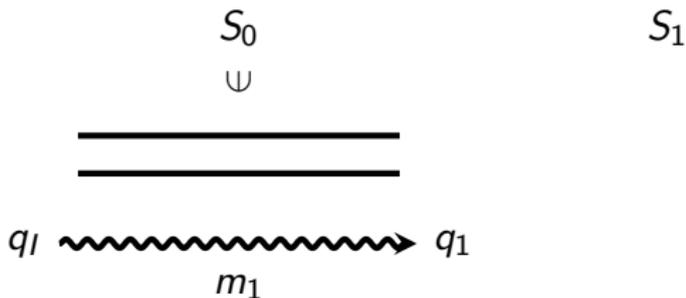
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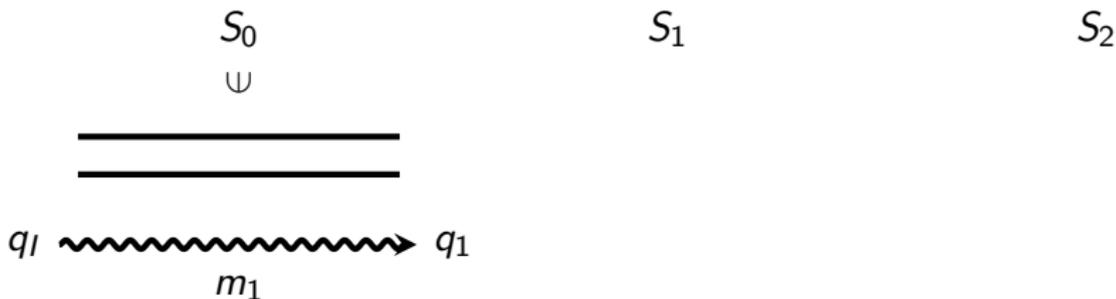
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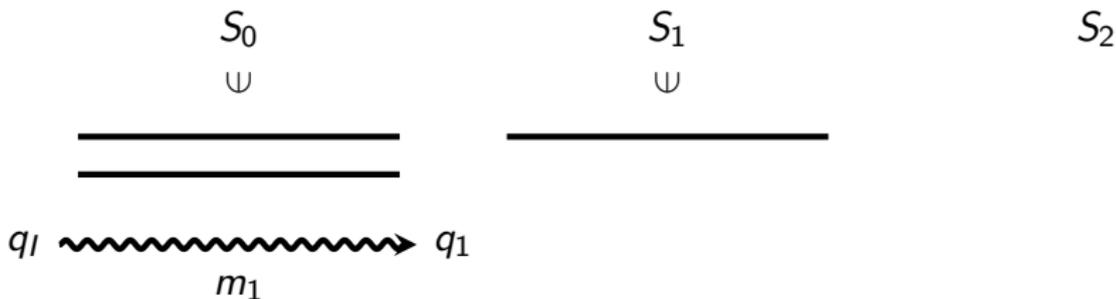
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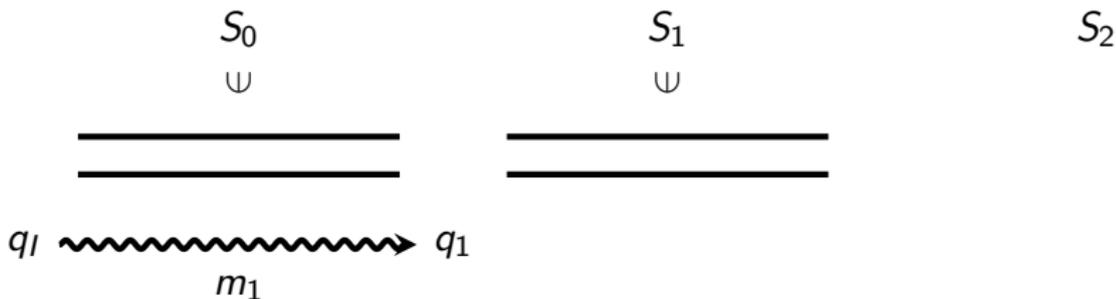
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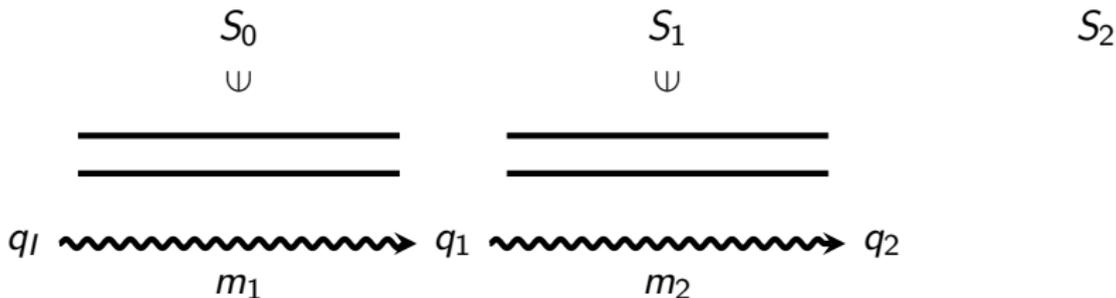
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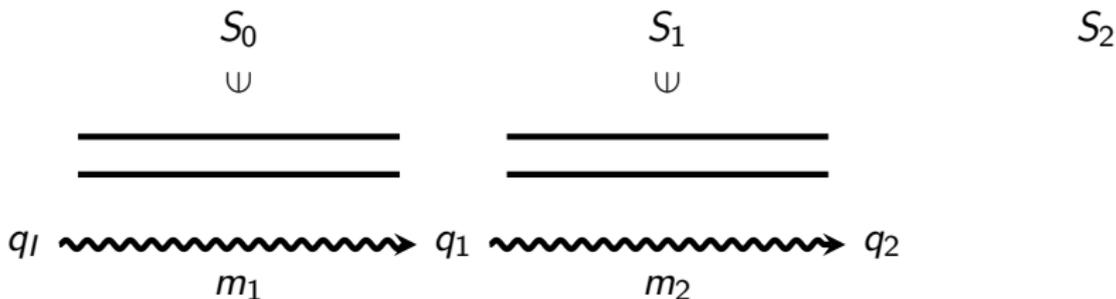
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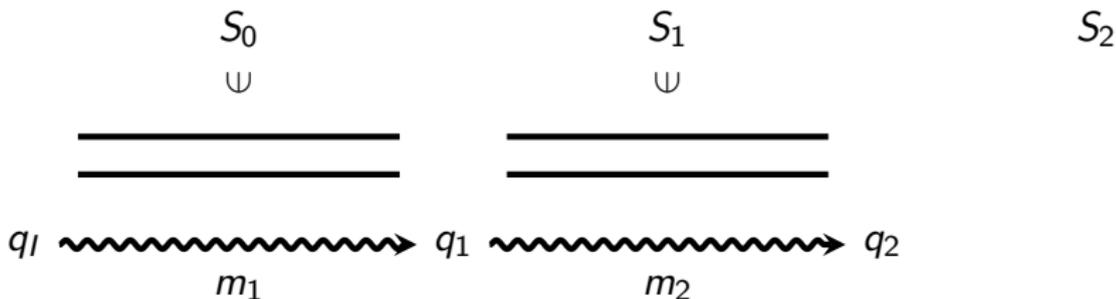


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- Player O wins if $m_1 m_2 \dots$ is aggregation of accepting run.
- This is a delay-free Gale-Stewart game!
- Automaton recognizing winning condition is (roughly) of size $\mathcal{O}(\text{index}(\equiv))$.

Main Theorem

Theorem

Let \mathcal{A} be an ω -automaton, let \mathfrak{M} be an aggregation for \mathcal{A} , and define $d = 2^{|\mathcal{Q}|^2 \cdot |M|}$.

1. If Player O wins the delay game with winning condition $L(\mathcal{A})$ for **any** lookahead, then she also wins the corresponding abstract block game.
2. If Player O wins the abstract block game, then she also wins the block game with winning condition $L(\mathcal{A})$ and block size d .
3. Moreover, if she has a finite-state winning strategy for the abstract game, then she has a finite-state winning strategy of the same size for the block game.

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Corollary

Solving delay games equivalent to solving abstract block games and constant lookahead $2d$ is sufficient.

Conclusion

Also in the Paper:

1. Another type of aggregation suitable for quantitative acceptance conditions.
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Unpublished (with Sarah Winter):

Recall that automata implementing finite-state strategies in block games process blocks \Rightarrow Exponentially-sized alphabets.

1. Implement transition and output function as transducers.
2. Upper and lower bounds on size in both models.
3. Tradeoffs between these models.